

Optimization of Interactive Live Free Viewpoint Multiview Video Streaming Bandwidth

Richard Kramer, Member IEEE – Oregon State University

What if we could change *virtual* reality?... *into reality?*



Optimization of Interactive Live Free Viewpoint Multiview Video Streaming Bandwidth

"Today, there are no known streaming services that provide MVV [Multi-View Video] content to home users ...

... [because it is] infeasible to perform transmission over fixed bitrate channels ..." [Dufaux2013]

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What if we could change *virtual* reality?... *into reality?*



Agenda

- Background
 - Video Compression and SVC (Scalable Video Coding)
- Multiview Video Types
 - Multiview Coding (MVC) Types and Industry Standards
- State of the Industry FTV (Free Viewpoint TV)
- OLFVmv (Optimized Live Free Viewpoint multiview video)
 - Motivation
 - Contribution
 - Architecture
 - Algorithms
- Simulation Results
- Extensions to OLFVmv Using Network Coding
- Further Optimization of OLFVmv Ph.D. Thesis Work
- Conclusion



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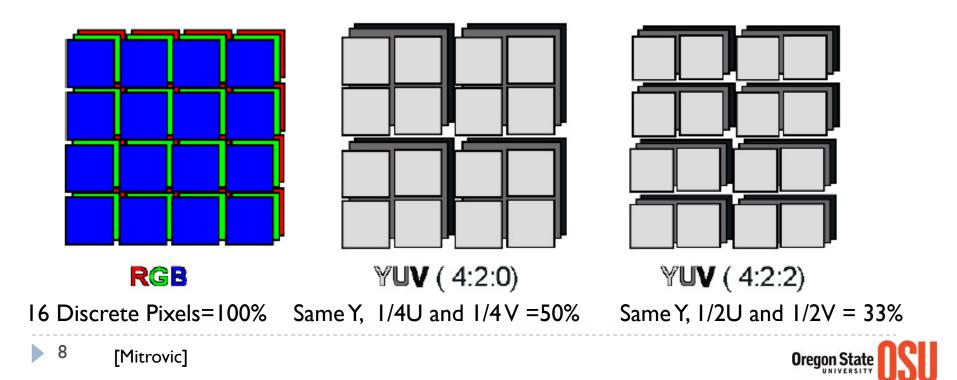


- Video Compression Steps
- Step 1: Reduction of Resolution
- Step 2: Motion Estimation
- Step 3: Discrete Cosine Transform (DCT)
- Step 4: Quantization
- Step 5: Entropy Coding



Step 1: Reduction of Resolution

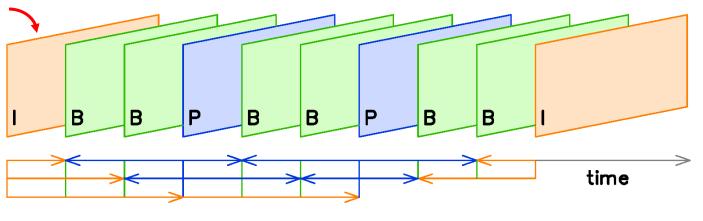
Visual perception of color space (U and V) is much lower than to Luminance (Y). Thus color information for U and V can be combined more so than for Y.



Step 2: Motion Estimation

- MPEG employs multiple Frame Types
 - I (Intra) Frames Spatially encoding of entire image
 - P (Prediction or Inter-Predication) Frames Uses information from <u>ONE</u> reference point in time to create an image
 - B (Bi-Directional) Frames Uses information from <u>TWO</u> reference points in time to create an image





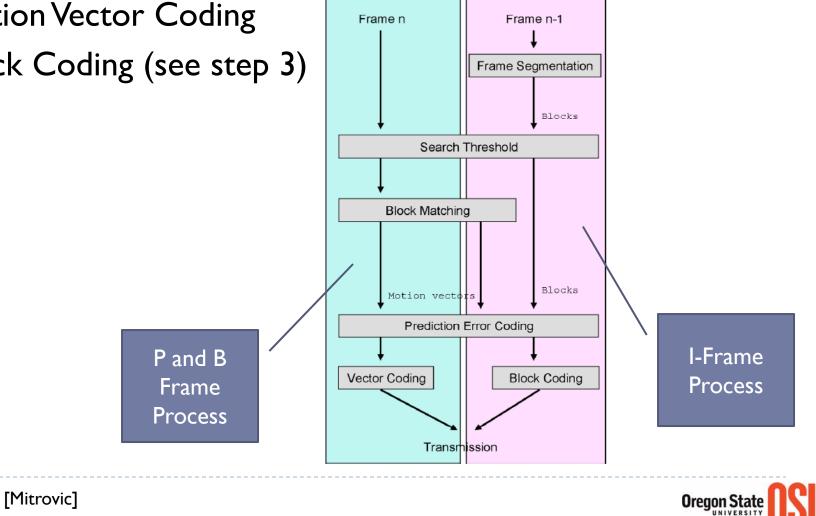


Step 2: Motion Estimation – entails numerous sub-steps

Motion Vector Coding

10

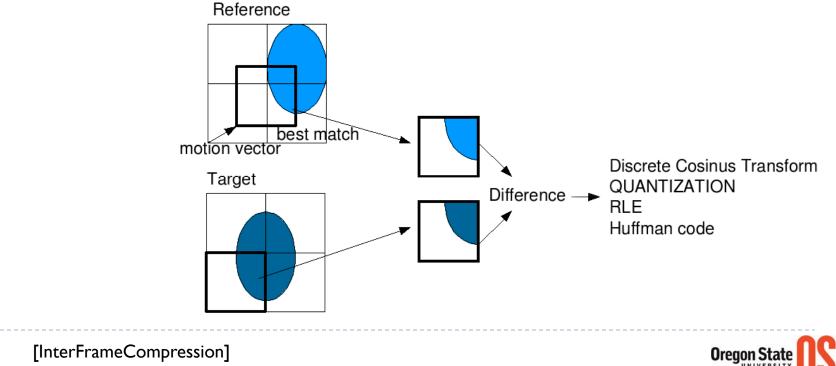
Block Coding (see step 3)



Step 2: Motion Estimation – entails numerous sub-steps

Block Matching

A Block Matching Algorithm is used to look at the surrounding macroblocks to see if there is a match to the "Reference" macroblock

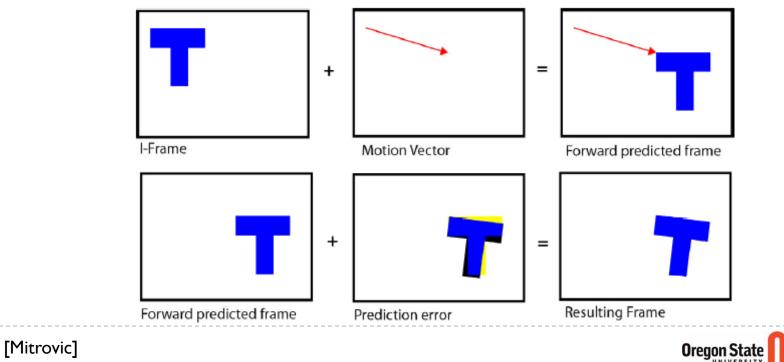


Step 2: Motion Estimation – entails numerous sub-steps

Motion Vector and Error Correction

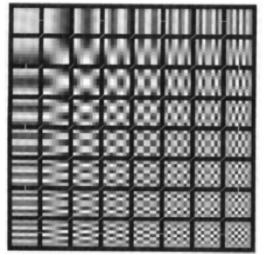
12

Once the matching macroblock is found and the correction is evaluated, a motion vector is generated identifying where to move the "Reference" macroblock + Error Correction



Step 3: Discrete Cosine Transform (DCT)

- Each macroblock is analyzed to determine the contribution of EACH of the below 64 visual "frequencies".
- The associate "weights" of each of the 64 DCT possible frequencies are called the "DCT coefficients"

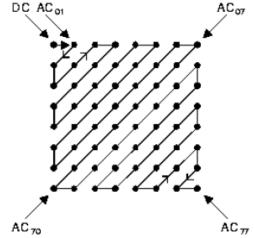




Step 4: Quantization

Based on the desired quality level, the 64 DCT coefficients are then additionally scaled based on human visual perception, e.g., higher frequency components are less noticeable to humans thus are given less weight (or set to zero)

The results of the 64 quantized DCT coefficients are then stored in a zig-zap pattern





Step 5: Entropy Coding

The DCT differentials are then calculated using variablelength codes to obtain further compression.

Category C	Range of <i>DIFF</i> value	Example codeword			
0	0	00			
1	-1, 1	010			
2	-3, -2, 2, 3	011			
3	-74, 47	100			
4	-158, 815	101			
5	-3116, 1631	110			
6	-6332, 3263	1110			
7	-12764, 64127	11110			
8	-255128, 128255	111110			
9	-511256, 256511	1111110			
10	-1023512, 5121023	11111110			
11	-20471024, 10242047	111111110			

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Multiview Video Types

The H.264/MPEG4 MVC (Multiview Coding) Standard was first approved in July 2008

Integrated into 5th Edition of H.264/MPEG-4 Std. ISO/IEC 14496-10 (Annex H)

Two specific Multiview "Profiles" are supported:

I) Stereo High Profile, also known as "3D" or "2D plus Delta"

- Used for 3D movies including Blue-Ray
- Various methods are employed to display 3D movies (glasses, holographic displays, etc.
- 2) <u>Multiview High Profile</u> supports an arbitrary number of views, also know as "Free-viewpoint Vide o" or "FTV" (Free-viewpoint TV)

FTV is used for example, to obtain differing views of a field in a sports competition, such as soccer.

Important H.264/MPEG4 Revisions:

Version 12: (March 9, 2010) Amendment containing definition the **Multiview Stereo High profile** for two-view video coding with support of interlaced coding tools and specifying an additional SEI message (the frame packing arrangement SEI message).

Version 18: (April 13, 2013) Amendment to specify the coding of depth map data for 3D stereoscopic video, including a **Multiview Depth High profile**.

7 [ISO/IEC 14496-10:2008][ISO/IEC 14496-10:2009][ISO/IEC 14496-10:2010][ISO/IEC 14496-10:2014]



Version 11: (March 16, 2009) Major addition to H.264/AVC containing the amendment for Multiview Video Coding (MVC) extension, including the **Multiview High profile**.

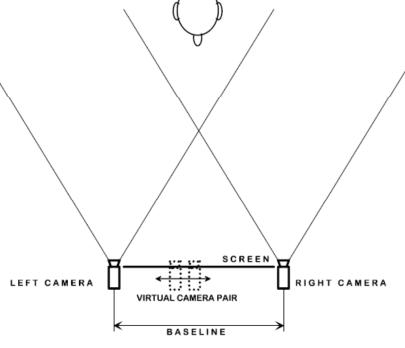
1) Stereo/3D Multiview Video

Typically two (2) cameras, the primary view and associated depth map(s) is encoded

- Generate synthesized views using video and depth
- At minimum: One video, one depth map

Technologies required:

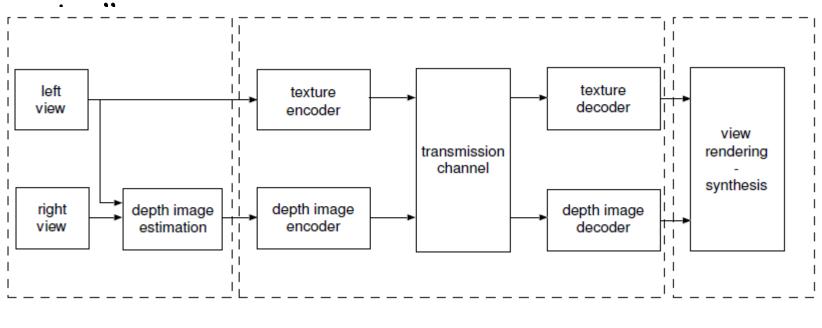
- Depth estimation
- Depth encoding
- View synthesis





1) Stereo/3D Multiview Video

For MVC (Multiview Coding), a "based frame" is used (for example, the "left view" and relative to that, and only prediction information is transmitted relative to the "right

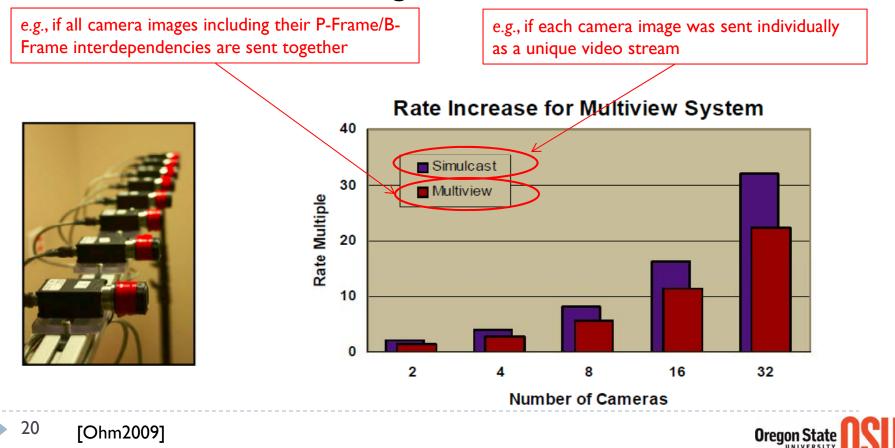


Multiview images Coding, transmission and decoding Multiview synthesis acquisition



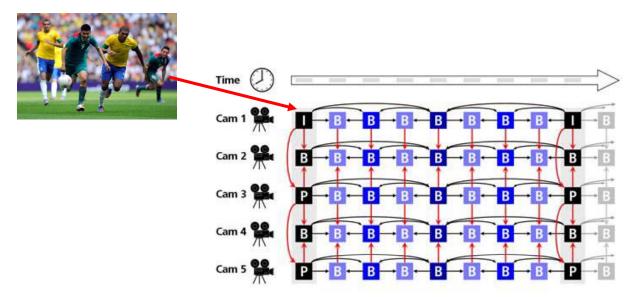
2) High Profile / FTV Multiview Video

Multiple cameras whereas what is displayed is either part of an actual image, or a synthetic image, created by a combination of other images.



2) High Profile / FTV Multiview Video

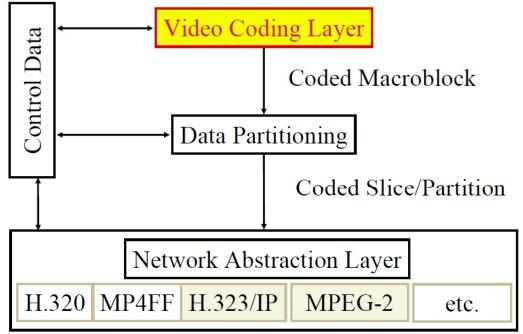
 Multiview video contains a large amount of inter-view statistical dependencies, therefore those dependencies can be exploited.





MVC (Multiview Coding) Layering

- MPEG-4 SVC (Scalable Video CODEC) allows for the dynamic video quality reception based on differing receiver input bandwidths across an entire system.
- The base layer is always used. The image information is encoded at the Video Coding Layer (VCL) and Transported in the higher Network Abstraction Layer (NAL).





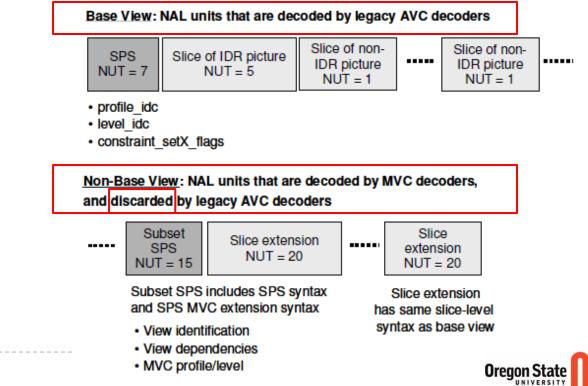
MVC (Multiview Coding) Layering

NAL messages are call "units"

23

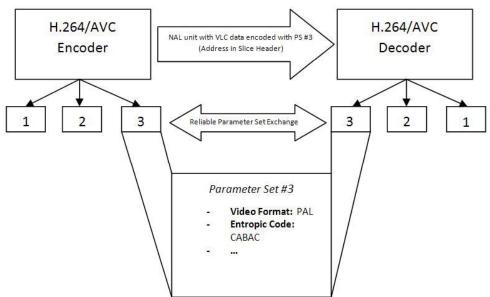
[SchierlNarasimhan2011]

- There are <u>multiple</u> "types" of NAL units that convey both VCL and non-VCL information.
- Each NAL unit type is called an NAL Unit Type ("NUT").



MVC (Multiview Coding) Layering

- MVC exploits significant sharing of common information between views.
- Common (non-VCL) information for all views can be sent via a separate communications path than the VCL data
 - SEI (Supplemental Enhancement Information)
 - Parameter Sets





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State of the Industry for FTV MVC

"Today, there are no known streaming services that provide MVV [Multi-View Video] content to home users ... the fundamental reasons for this can be listed as:

- (i) lack of specifications for MVV, such as resolution and number of views, making it difficult to create universal content that is suitable for all multiview displays;
- (ii) heterogeneous bandwidth requirement of different multiview displays, making it infeasible to perform transmission over fixed bit-rate channels ..."



State of the Industry for FTV MVC

The last apparent effort to drive standardization related to FTV *transport* appears to be a European initiative called "DIOMEDES" (DIstribution Of Multi-view Entertainment using content aware DElivery Systems).

... which primarily ended in 2012

... and was never deployed





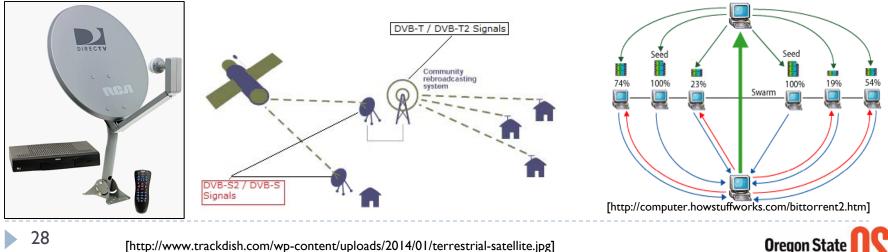
DIOMEDES offered:

A DVB (Direct Video Broadcast) / DTH (Direct to Home) medium

Digital Video Broadcasting (DVB) is a set of standards that define digital broadcasting using existing satellite, cable, and terrestrial infrastructures

Combined with a P2P (Peer to Peer) medium

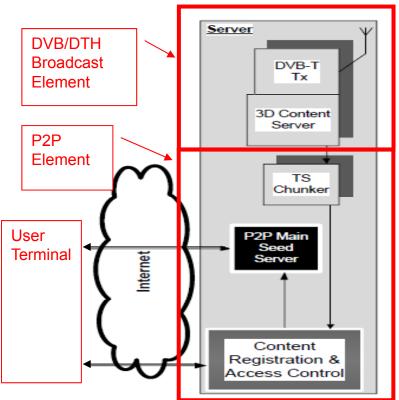
A P2P network is created when two or more PCs are connected and share resources without going through a separate server computer





 DIOMEDES offered a DVB (Direct Video Broadcast) / DTH (Direct to Home) medium combined with a P2P (Peer to Peer) medium

Notably in DIOMEDES, the P2P Main Seed Server did not provide a feedback mechanism related to the desired content from the user terminals.



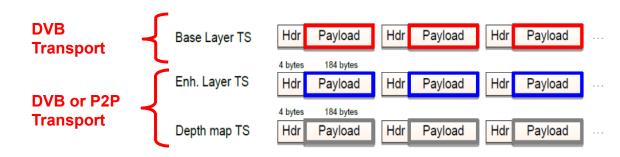
DIOMEDES DVB + P2P FTV Architecture



DIOMEDES employed SVC layering for the:

- Base layer
- Metadata layer (e.g., depth map)
- Enhanced Layer

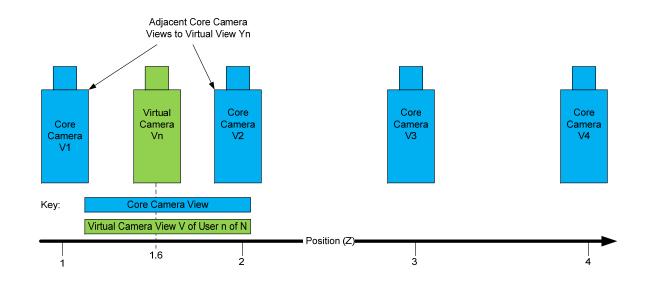
Based on the layer, either the DVB or P2P medium was used



Splitting of content into multiple Transport Streams



Using an array of "Core Cameras" (e.g., V1, V2, ...) virtual views are created using two adjacent core camera views





In DIOMEDES, video content GOP (Group of Picture) "Chunks" were assigned priorities 1-16, where the Base and Metadata layers shared the same priority for core cameras V2-V8

three camera group (V1-3)

View priority order (View-	V1	V2	V3	V4	V5	V6	V7	V8
ID)								
Base PID	P=1	P=3	P=4	P=8	P=10	P=12	P=14	P=16
Enhancement PID	P=5	P=6	P=7	P=9	P=11	P=13	P=15	P=17
Depth PID	P=2	P=3	P=4	P=8	P=10	P=12	P=14	P=16

Prioritization of GOP chunks over transport streams

DIOMEDES take-aways:

- There is no feedback mechanism from the user terminals on what video is most desired
- ... but rather, the video content priority is based on core camera "V1"
- DIOMEDES requires impractical broadcast channel bandwidth



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Motivation – for Optimized Live Free Viewpoint multiview video (OLFVmv)

 There is a need for <u>a practical transport</u> of FTV over existing broadcast mediums:

- Using DVB bandwidths more efficiently
- There is a need for <u>a practical transport</u> of FTV over P2P networks:
 - Enable low bandwidth, mobile P2P networks using as little as 2 Mbps

3) Offering superior performance



Motivation

Prioritize Content based on what people want to see...

... because not all content is equally important to the overall viewing audience.

Core



Core

Camera



Core

Camer



Core

Camer

Contribution – Optimized Live Free Viewpoint multiview video (OLFVmv)

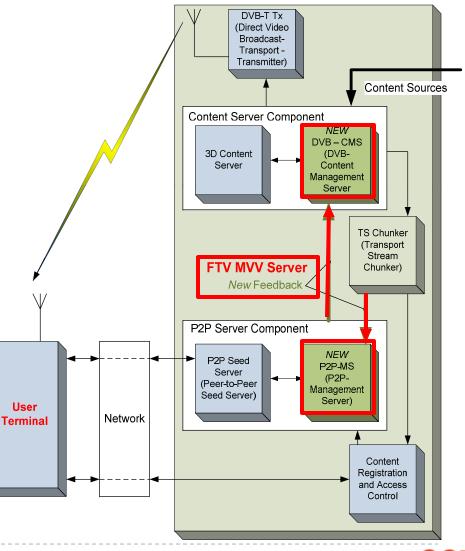
1) Improvements / Contributions:

- (a) An improved architecture
- (b) Intelligent algorithms combined with the improved architecture to predict what video content is important
- 2) A roadmap to other improvements:
- Network coding for the remaining data to be sent via the P2P network

OLFVmv – Improved System Architecture

Improvements:

- A new "P2P-Management Server" ("P2P-MS") to perform the content selection/prioritization algorithms and provide feedback to the DVB broadcast system, and
- A "DVB-Content Management Server" ("DVB-CMS") to receive input from the P2P-MS on the most prevalent (requested views) video content to broadcast, and based on that input, to select the most prevalent content to be broadcast over the two DVB broadcast channels



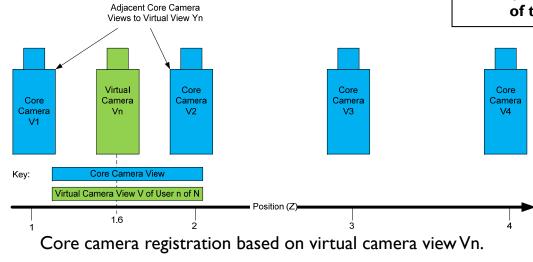
Oregon State

OLFVmv – Algorithms Overview

The OLFVmv system utilizes each viewers desired viewing position, "Vn" For discussion purposes:

Integer "Vx" is defined to be a specific primary core camera view for a user, called the *left* core camera view, and "Vx+1" is the core camera view immediately adjacent to the *right* of "Vx".

Non-Integer "Vn" is defined as a synthetic (simulated) desired view from the combination of two adjacent core camera views.





OLFVmv – Algorithms Overview

With limited resources over the DVB and P2P networks, <u>determine: what is content is most relevant</u>?

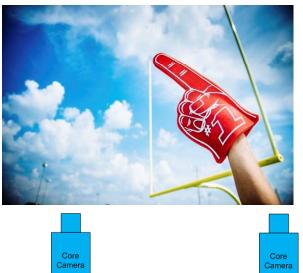
How? By developing intelligent algorithms

How many viewers want to see this **and what is the trend**?





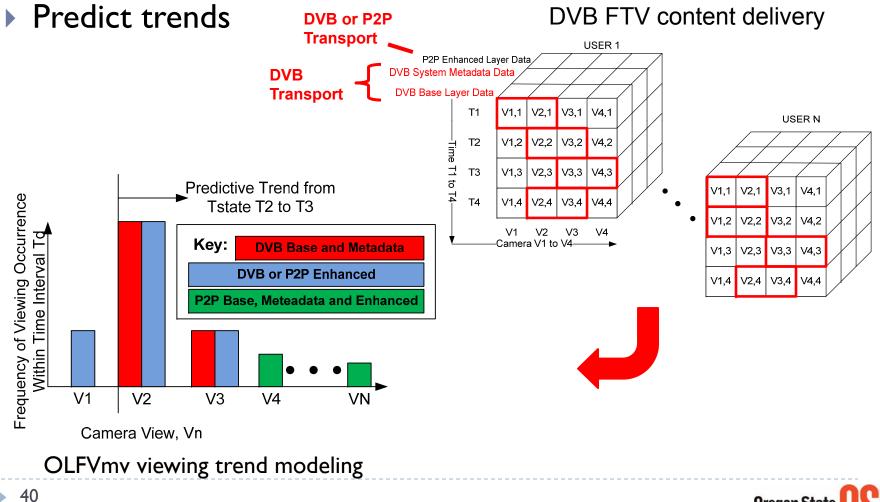
How many viewers want to see this **and what is the trend**?





OLFVmv – Algorithms Overview

Track viewing patterns over time





OLFVmv – Algorithms Step 1 – Assign Core Camera Views

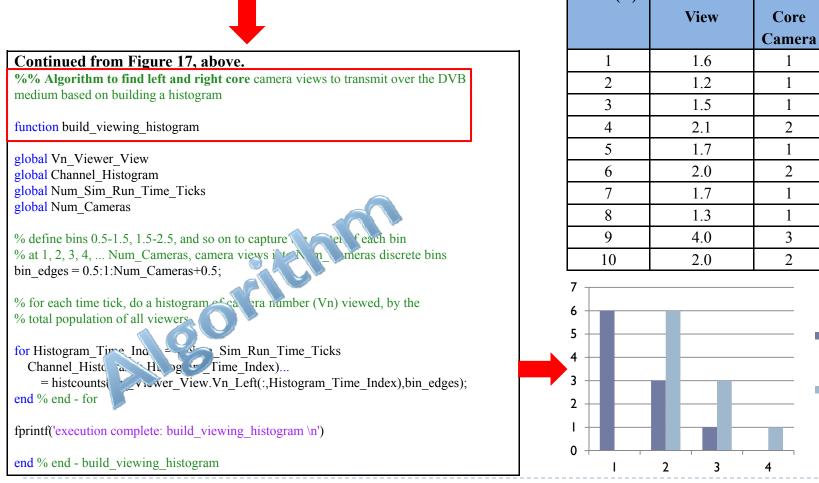
the following viewing pattern	User (N)	Vn Current View
%% Camera view registration algorithm	1	1.6
unction register cameras views	2	1.0
global Num Cameras	3	1.5
global Vn_Viewer_View	4	2.1
global Viewer_Time_Osc_Position global Viewer Random Position Offset	5	1.7
	6	2.0
% Virtual desired view = mean viewing position, plus/mi, ra on affset % This operation takes the offset matrix [Num_jew x 1 nd adds to the	7	1.7
% View Position matrix [1 x Time Ticks] and ear sa exposition for each	8	1.3
% viewer = [Num_Viewers x Time Ticks]	9	4.0
Vn_Viewer_View.Vn = min(max((Viewer_Tone_Control of the Viewer_Random_Position_Offset),1),Num_Cameras);	10	2.0
% Calculate left i mer by no ting Vn in to an integer with the % minimum came b amera - 1 and the right most camera being one from % the, Camera = 1 and Cameras - 1 Vn_Viewer_View. n_Left = floor(min(max(Vn_Viewer_View.Vn,1),Num_Cameras - 1));		
% Calculate right most camera by taking Vn_Viewer_View.Vn_Left and adding % one. The case should never exist where the Right most camera exceeds % Num Cameras, but if it does, limit it to Num Cameras		
Vn_Viewer_View.Vn_Right = int8(min((Vn_Viewer_View.Vn_Left + 1),Num_Cameras));		
printf('execution complete: register_cameras_views \n')		
end		

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OLFVmv – Algorithms Step 2 - Histogram Creation

Step 2: Use previous output to create histogram



Vn Lef

t[N]

Left

Vn

Current

User (N)

Vn Rig

ht[N]

Right

Core

Camera

2

2

2

3

2

3

2

2

4

3

Left Core

Camera

Frequency

Right Core

Camera Frequency

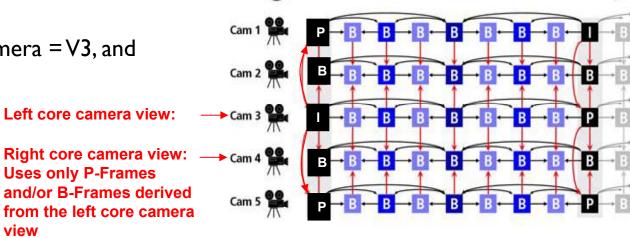


OLFVmv – Algorithms Step 3 – Determine DVB Channel Content

Step 3: Determine most prevalent LEFT and RIGHT camera views and assign those to the DVB channels Time

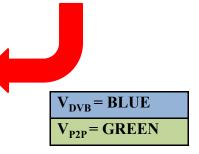
Example: Let LEFT camera = V3, and **RIGHT** camera be V4

view



Temporal P and B-Frame view prediction structure for MVC

Core Camera View →	V1	V2	V3	V4	V5	V6	V7	V8	
Base Layer	P2P	P2P	DVB	DVB	P2P	P2P	P2P	P2P	
Metadata Layer	P2P	P2P	DVB	DVB	P2P	P2P	P2P	P2P	
Enhanced Layer	P2P	P2P	DVB	DVB	P2P	P2P	P2P	P2P	



Example of video content distribution between the DVB and P2P channels



OLFVmv – Algorithms

Step 4 – Determine P2P Channel Content

- Step 4: Set the LEFT and RIGHT most prevalent base, metadata and enhanced layers to a priority such that the content is transported over the DVB channel
- ... and everything else over the P2P channel

Let
$$V_{ALL} = V_{Meta}[m] + V_{Base}[m] + V_{Enhanced}[m])$$

Then:
 $V_{P2P} = V_{ALL} - V_{DVB}$



OLFVmv – Algorithms Step 4 – Set DVB and P2P Content Priorities

Not Set primits make the UAPW. Each we for a different layer 1 = Base, 2 = Metadam, 3 = Eakaard Get medication 1 = Config the file baseling for cames 7 < 4 (1) MVV Came 1, Primer Make (1) = - (1) MVV Came 1, Primer Make (1) = -	Continued from Figure 19, above.	
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GLYMV Channel (Proteins, Made (OLFVMV Channel Priorities_Mask (:,:,2)= [7 1 2 10 13 16 19 22; 8 3 4 11 14 17 20 23;	for camera 6 <-7
GLYMV Channel Proteins, Mak (:,SP- (2) 99 571 210 (3) 21 595 64 21 83); for treat carners. Science flow (fig belos-sight) for carners 4 - 5 GLYMV Channel Proteins, Mak (:,SP- (2) 99 571 210 (3) 21 99 55 21 216; for 10 91 71 210 (3) 21 91 59 56 21 216; for 10 91 71 210 (3) 21 91 59 56 21 216; for 10 91 71 210 (3) 21 91 59 56 21 216; for 10 91 71 210 (3) 21 91 59 56 21 216; for 10 91 71 210 (3) 21 91 59 56 21 216; for 10 91 71 210 (3) 21 91 59 159 56; for 10 91 71 210 (3) 21 91 59 159 56; for 10 91 71 210 (3) 21 18 159 56 4; for 10 91 10 71 1; for 20 91 71 210 (3) 21 18 159 56 4; for 10 91 10 71 1; for 20 91 71 210 (3) 21 18 159 56 4; for 10 91 10 71 1; for 20 91 71 210 (3) 21 118 129 56 4; for 10 91 10 71 1; for 20 91 71 10 71 10 71 1; for 20 91 71 10	OLFVMV_Channel_Priorities_Mask (:,:,3)= [13 7 1 2 10 16 19 22; 14 8 3 4 11 17 20 23;	for camera 5 < 6
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Max, Hangam, Canera, Cont ¹ , ¹ Le May, ¹ Jiang, ¹ Le May,	[22 19 16 13 10 7 2 1 ; 23 20 17 14 11 8 4 3 ;	s n = Num_Layers*Num_Cameras is the low="2P priori s: Determine what highest count is in histophd for wh is a count at where each row number whe camera = count of a count of the row of the count of
5. Num_(amerase N + 1 free Tomp Mark, Index = Num, Cameras - Max, Histogram, Camera, Index + 1; Chamel Provider: "Histogram, Time, Index/Type, Index, OleX'Mus) = flip#004FMWV, Chamel Privrities_Mark(,Temp, Mark, Index); end % end = if print[recording complete: set, OLEYMV, chamel provides _init to) med% end = ar OLEYMV chamel provides _init		<pre>km , lingum</pre>

45

$V_{DVB} = BLUE$
V _{P2P} = GREEN

Priority: I = Most Important 24 = Least Important

Core Camera View →	V1	V2	V3	V4	V5	V6	V7	V8
Base Layer	P2P	P2P	DVB	DVB	P2P	P2P	P2P	P2P
Metadata Layer	P2P	P2P	DVB	DVB	P2P	P2P	P2P	P2P
Enhanced Layer	P2P	P2P	DVB	DVB	P2P	P2P	P2P	P2P

Algorithm Input

OLFVmv video content distribution between the DVB and P2P channels at T-State = I

Core Camera View→	V1	V2	V3	V4	V5	V6	V7	V8
Base Layer	13	7	1	2	10	16	19	22
Metadata Layer	14	8	3	4	11	17	20	23
Enhanced Layer	15	9	5	6	12	18	21	24

OLFVmv – Algorithms Step 5 – Establish a Trend/Update Priorities

 $V_{DVP} = BLUE$

	% Test to see the max camera is at either end, and if so, set the mask									
Continued from Figure 25, above.	% trending from the end	U. ODDENI								
%% Figure 27 from Thesis for - Set DVB and P2P channel priorities for OLFVmv	if (Max_Histogram_Camera_Index_Current == 1) (Max_Histogram_Camera_Index_Current == Num_Cameras)	$V_{P2P} = GREEN$								
function set_OLFVMV_channel_priorities global Channel_Priorities global Channel_Histogram	Channel_Priorities(:,:,Histogram_Time_Index,Type_Index_OLFVmv) =	OLFVmv video		t distri	bution	betwe	en the	DVB a	nd P2P	1
global Num_Cameras global OLFVMV_Channel_Priorities_Mask global Num_Sim_Run_Time_Ticks global Type Index OLFVmv	OLFVMV_Channel_Priorities_Mask(:,:;,Max_Histogram_Camera_Inde x_Current);	channels at T-Sta	te = I				1			
% Priorities for each camera, lowest number = highest P2P priority, % highes number n = Num_Layers*Num_Cameras is the lowest P2I	% Otherwise, must be cameras 2 through Num_Cameras-1, so determine if the % trend is from the left to right. Default is to the right.	Core Camera	V1	V2	V3	V4	V5	V6	V7	V8
priority % Starting with T=2 and for each time tick after, take the histogram	% Compare where the current max camera histogram point is the current	View →					,,,		,,,	, 0
results % from the last T-State, compare them to the current T-State, determine if the	% T-State compared to where it was in the last T-State. If the current % T-State index is greater, then the trend is to	Base Layer	13	7	1	2	10	16	19	22
% trend is to the left or right and set the priority mask accordingly Max_Histogram_Camera_Index_Last = 1; % Initialized the	elseif (Max_Histogram_Camera_Inde Max_Histogram_Camera_Index_La,	Metadata Layer	14	8	3	4	11	17	20	23
previous T-State as 1 for Histogram_Time_Index = 2:Num_Sim_Run_Time_Ticks	% If so, set the ma Temp_M'sk_Ipdo fax_ ogra _Camera_Index_Current;	Enhanced Layer	15	9	5	6	12	18	21	24
% Determine what highest count is in histogram for this T-State	Chan_Prio_::Histo_Time_Index,Type_Index_OLFVmv)	·								
% betermine what ingrest count is in instogram for this 1-state and % what camera number each occurred at. The function find return									Transma d	
and % what camera number each occurred at. The function find return tow % and column so this needs to be reduced to just column.	therwise rend must be to the left so flip the mask over so the orities go toward the left, using a transposed index of the mask,		listog	ram l	Jpdat	te / D	eterr	nine 1	Frend	
and % what camera number each occurred at. The function find return row % and column so this needs to be reduced to just column. Max_Histogram_Camera_Count_Current = max(Channel_Histogram(:,Histogram_Time_Inde	s therwise arend must be to the left so flip the mask over so the		Ŭ							
and % what camera number each occurred at. The function find returr row % and column so this needs to be reduced to just column. Max_Histogram_Camera_Count_Current =	therwise - trend must be to the left so flip the mask over so the prities go toward the left, using a transposed index of the mask, e.g. % N=1 -> Num_Cameras, N=2 -> Num_Cameras -1, thus Index =	Viev	wing tre	ram (and from (Left cor	n T-State	e =1 to	View _=1 to	ving trer T-State	nd from	T-Sta
and % what camera number each occurred at. The function find return row % and column so this needs to be reduced to just column. Max_Histogram_Camera_Count_Current = max(Channel_Histogram_Camera_Inde; for Max_Histogram_Camera_Inde; % find the first, "urrease to a bin ce, we could if Max_Histogramvers," urtent =	<pre>5 6 6 6 7 6 7 7 7 8 7 8 7 8 7 8 7 8 7 8 7</pre>	Viev	wing tre	nd from	n T-State	e =1 to	View	ving trer T-State	nd from	T-Sta
and % what camera number each occurred at. The function find return row % and column so this needs to be reduced to just column. Max_Histogram_Camera_Count_Current = max(Channel_Histogram_Cirikitogram_Time_Index) for Max_Histogram_Camera_Index. % and the first surrease the the first su	<pre>state of the set of the left so flip the mask over so the prities go toward the left, using a transposed index of the mask, e b // (*********************************</pre>	Viev	wing tre	nd from	n T-State	e =1 to	View _=1 to	ving trer T-State	nd from	T-Sta
nd % what camera number each occurred at. The function find returr ow % and column so this needs to be reduced to just column. Max_Histogram_Camera_Count_Current = nax(Channel_Histogram(,Histogram_Time_Inde- for Max_Histogram(_Camera_Inde), rrent	<pre>state of the state of the</pre>	Viev	wing tre ate = 2	nd from (Left coi	re view)	e =1 to	View =1 to view	ving tren o T-State)	nd from e = 2 (Ri	T-Sta ght co
and % what camera number each occurred at. The function find return two % and column so this needs to be reduced to just column. Max_Histogram_Camera_Count_Current = max(Channel_Histogram_Camera_Index_urrent_LossCameras % ind the firsturrent_LossCameras % ind the firsturrent_LossCameras % ind the firsturrent_LossCameras % of the firsturrent_LossUrrent_Histogram_ if Max_Histogram_Maxurogramera_Index_Current,Histogram_ Channel_Histogram(Maxurogramera_Index_Current,Histogram_ % oreak to preserve the index break	<pre>herwise - trend must be to the left so flip the mask over so the prities go toward the left, using a transposed index of the mask, c_B, % N= 1 -> Num_Cameras, N= 2 -> Num_Cameras -1, thus Index = % Num_Cameras - N + 1 else Temp_Mask_Index = Num_Cameras - Max_Histogram_Camera_Index_Current + 1; Channel_Priorities(;;;Histogram_Time_Index,Type_Index_OLFVmv) = flipIr(OLFVMV_Channel_Priorities_Mask (;;Temp_Mask_Index)); end % end - if % now that we are done testing, remember the index where the max camera % occurred for the next loop. Thus_Current becomes _Last.</pre>	Viev T-St	wing tre	nd from	n T-State	e =1 to	View _=1 to	ving trer T-State	nd from	T-Sta
and % what camera number each occurred at. The function find return row % and column so this needs to be reduced to just column. Max_Histogram_Camera_Count_Current = max(Channel_Histogram_Camera_Index_Current, Histogram_Camera_Index) for Max_Histogram_Camera_Index_Current, Histogram_Tame_Index) % oreak to preserve the index break end % end - for Max_Histogram_Camera_Index_Current =	<pre>state of the set of the left so flip the mask over so the spritter go toward the left, using a transposed index of the mask, c_L, where the set of the mask, c_L, where the set of the set of the mask, c_L, where the set of the set of the mask over so the set of the mask, c_L, where the set of the set of the mask, set of the set of the set of the set of the mask over so the set of the set of the mask over so the set of the</pre>	View T-St Core Camera View →	wing tre ate = 2 V1	end from (Left cor V2	v3	e =1 to	View =1 to view V5	ving tren o T-State) V6	nd from e = 2 (Ri V7	T-Stat ght co V8
and % what camera number each occurred at. The function find return row % and column so this needs to be reduced to just column. Max_Histogram_Camera_Counc_Current = max(Channel_Histogram_Camera_Index_Current, Histogram_Camera_Index) for Max_Histogram_Camera_Index_Current, Histogram_Camera_Index % The the first surrease because if Max_Histogram_Camera_Index_Current, Histogram_Camera_Index % oreak to preserve the index break end % end - if end % end - for Max_Histogram_Camera_Index_Current =	<pre>herwise</pre>	View T-St Core Camera View → Base Layer	wing tre ate = 2 V1 19	v2	v3	e =1 to V4 1	View =1 to view V5 2	ving tren o T-State () V6 10	nd from e = 2 (Ri V7 16	T-Star ght co V8 22
and % what camera number each occurred at. The function find return row % and column so this needs to be reduced to just column. Max_Histogram_Camera_Counc_Current = max(Channel_Histogram_Camera_Index_Current, Histogram_Camera_Index) for Max_Histogram_Camera_Index_Current, Histogram_Camera_Index % The the first surrease because if Max_Histogram_Camera_Index_Current, Histogram_Camera_Index % oreak to preserve the index break end % end - if end % end - for Max_Histogram_Camera_Index_Current =	<pre>herwise tend must be to the left so flip the mask over so the prities go toward the left, using a transposed index of the mask, c_B. > N=1 -> Num_Cameras, N=2 -> Num_Cameras -1, thus Index = > Num_Cameras - N + 1 else Temp_Mask_Index = Num_Cameras - Max_Histogram_Camera_Index_Current + 1; Channel_Priorities(:;;Histogram_Time_Index,Type_Index_OLFVmv) = fiplr(OLFVMV_Channel_Priorities_Mask (;;,Temp_Mask_Index)); end % end - if % now that we are done testing, remember the index where the max camera % occurred for the next loop. Thus_Current becomes _Last. Max_Histogram_Camera_Index_Last = Max_Histogram_Camera_Index_Current; end % end - for Histogram_Time_Index =</pre>	View T-St Core Camera View →	wing tre ate = 2 V1	end from (Left cor V2	v3	e =1 to	View =1 to view V5	ving tren o T-State) V6	nd from e = 2 (Ri V7	T-Stat ght co V8

OLFVmv video content distribution between the DVB and P2P channels at T-State = 2...N

DIOMEDES Versus OLFVmv Priorities

In contrast, DIOMEDES transports 3 **fixed** channels (V1,V2, and V3) via DVB

For the P2P channels, DIOMEDES sets the Base and Metadata layers at a higher priority than the Enhanced layer

Core Camera View→	V1	V2	V3	V4	V5	V6	V7	V8
Base Layer	1	3	4	8	10	12	14	16
Metadata Layer	2	3	4	8	10	12	14	16
Enhanced Layer	5	6	7	9	11	13	15	17



[DIOMEDES D3.6 2011]



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Simulation Results

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- ▶ Further Optimization of OLFVmv Ph.D.Thesis Work
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Simulation Results - Baseline Assumptions

Description	Bandwidth Used per Channel (Mbits/s)
Video Content Bandwidth	For the primary DVB channel (e.g., left most DVB channel)
Requirements	• Primary Base (B) Layer = 6 Mbps
	• Primary Metadata (M) Layer = 2 Mbps
	• Primary Enhanced (E) Layer = $13.3 \text{ Mbps} \rightarrow 12 \text{ Mbps}$
	Total Primary B+E+M ~ 21.2 Mbps → 20 Mbps
	For an adjacent channel (e.g., any P2P or DVB channel other than the primary channel)
	• Adjacent Base (B) Layer = $6 \times (0.25x9+0.5x1)/10 = 1.65$ Mbps $\rightarrow 2$ Mbps
	• Adjacent Metadata (M) Layer = 2 Mbps
	 Adjacent Enhanced (E) Layer = 13.3 x (0.25x9+0.5x1)/10 = 3.66 Mbps → 4 Mbps
	Total Primary B+E+M ~ 7.3 Mbps → 8 Mbps
Channel Capacities	
DVB Channel Throughput (assume DVB-S, ATSC)	Assume 28 Mbps (e.g., 1 primary HDTV 3D channel (B+E+M) plus 1 adjacent HDTV 3D channel (B+E+M)
P2P Channel Throughput (assume no P2P or Network coding)	Mean_P2P_BW_Simulation_Rates = {2, 16, 32 and 64} Mbits/s, with Gaussian distribution of Sigma_P2P_BW = 0.1

Video Content Bandwidth Requirements and Assumptions



Simulation Results - Baseline Assumptions

Based on the assumptions provided, the following is an example of the assignment of bandwidth based on a given OLFVmv priority map:

DVB Channel Priority / Bandwidth
P2P Channel Priority / Bandwidth

Core Camera View →	V1	V2	V3	V4	V5	V6	V7	V8
Base Layer	19	13	7	1	2	10	16	22
Metadata Layer	20	14	8	3	4	11	17	23
Enhanced Layer	21	15	9	5	6	12	18	24

Example OLFVmv Priority Matrix

	-		-			-	-		
	Core Camera View →	V1	V2	V3	V4	V5	V6	V7	V8
	Base Layer	2Mbps	2Mbps	2Mbps	6Mbps	2Mbps	2Mbps	2Mbps	2Mbps
Mbps	Metadata	2Mbps	2Mbps	2Mbps	2Mbps	2Mbps	2Mbps	2Mbps	2Mbps
	Layer								
	Enhanced	4Mbps	4Mbps	4Mbps	12Mbps	4Mbps	4Mbps	4Mbps	4Mbps
	Layer			/					
	Total	8Mbps	8Mbps	8Mbps	20Mbps	8Mbps	8Mbps	8Mbps	8Mbps

Corresponding OLFVmv DVB Transport Bandwidth



Total DVB bandwidth = 28 Mb

Simulation Results - Baseline Assumptions

Based on the assumptions provided, the allocation for DIOMEDES

is as follows:

Core Camera View →	V1	V2	V3	V4	V5	V6	V7	V8
Base Layer	1	3	5	10	13	16	19	22
Metadata Layer	2	4	6	11	14	17	20	23
Enhanced Layer	7	8	9	12	15	18	21	24

DIOMEDES Priority Matrix

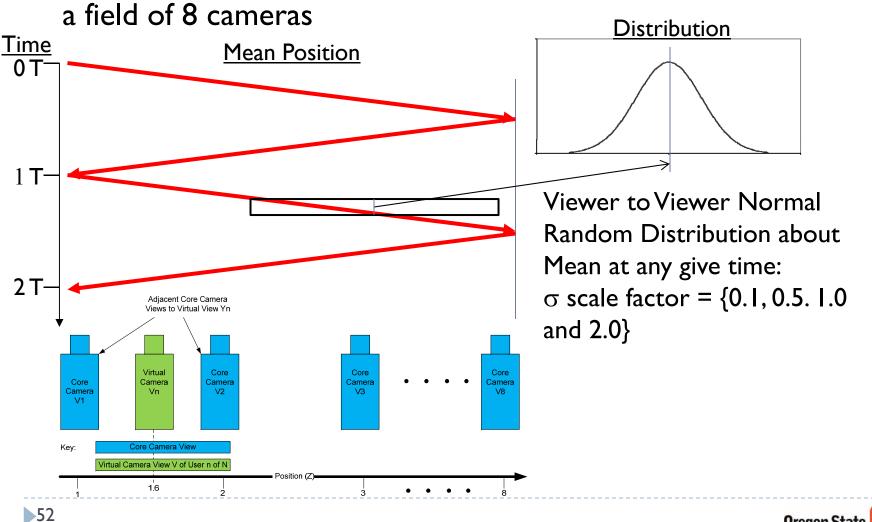
	Core Camera View→	V1	- V2-	V3	V4	V5	V6	V7	V8
	Base Layer	6Mbps	2Mbps	2Mbps	2Mbps	2Mbps	2Mbps	2Mbps	2Mbps
Total DVB bandwidth = 28 Mbps	Metadata Layer	2Mbps	2Mbps	2Mbps	2Mbps	2Mbps	2Mbps	2Mbps	2Mbps
	Enhanced Layer	12Mbps	4Mbps	4Mbps	4Mbps	4Mbps	4Mbps	4Mbps	4Mbps
	Total	20Mbps	8Mbps	8Mbps	8Mbps	8Mbps	8bps	8Mbps	8Mbps

Corresponding DIOMEDES DVB Transport Bandwidth



Simulation Parameters – Viewing Position for Each of N=100 Users

Viewer Oscillation Rate Period: $T = \{5, 10 \text{ and } 50 \text{ seconds}\}$ over





Simulation Parameters – Available P2P Bandwidth for Each of N=100 Viewers

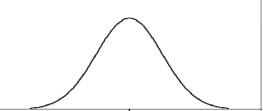
All Simulations run at each of the following mean P2P bandwidths:

Each User's Mean Available P2P Bandwidth2163264

For each user, at each bandwidth, a normal random variance scale factor of {0.1} x the Mean Bandwidth was applied

For example, assume a viewer with a Std Dev. of -2 and mean bandwidth of 32 Mbps:

 $-2 \times 0.1 \times 32$ Mbps = -6.4 Mbps



Thus 25.6 Mbps for a given user



For each of N=100 viewers, the performance of the OLFVmv system was contrasted against DIOMEDES in Matlab

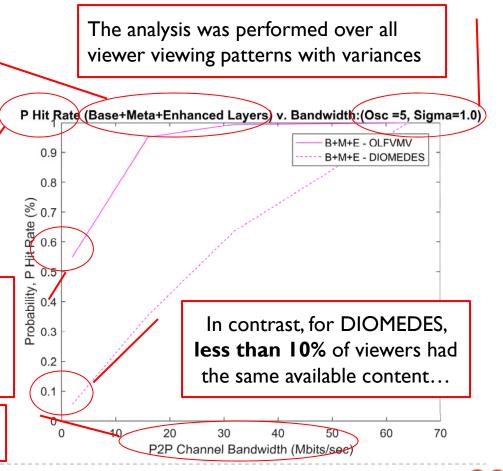
Example output:

All layer permutations were analyzed

For the given viewing simulation, the "P Hit Rate" represents the probability that the LEFT and RIGHT content was for (1) a given layer(s) for (2) a given viewer so that the viewer could synthesized the desired virtual view

In this example for OLFVmv, at 2 Mbps, 58% of the viewers had ALL layers of content to create a synthesized view with a FAST oscillation rate of T=5 sec and sigma = 1.0

The analysis was performed over all simulated bandwidths including impairments

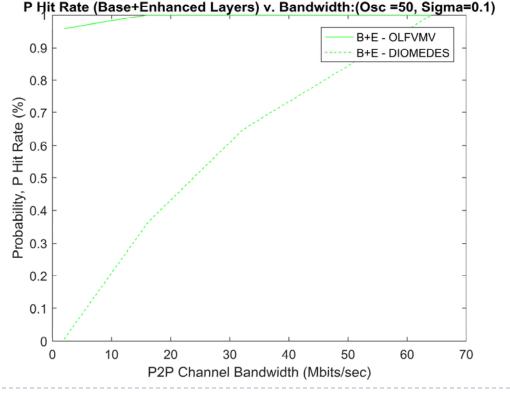


Oregon Sta



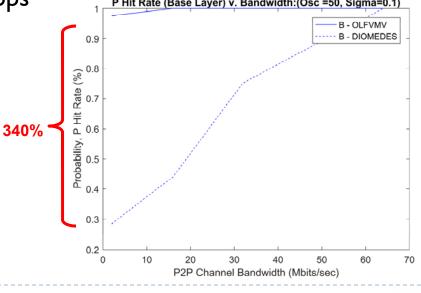
Overall, OLFVmv outperformed DIOMEDES for P2P bandwidths of less than 64 Mbps

Only at 64 Mbps did DIOMEDES' performance match that of OLFVmv P Hit Rate (Base+Enhanced Layers) v. Bandwidth:(Osc =50, Sigma=0.1)



Oregon State

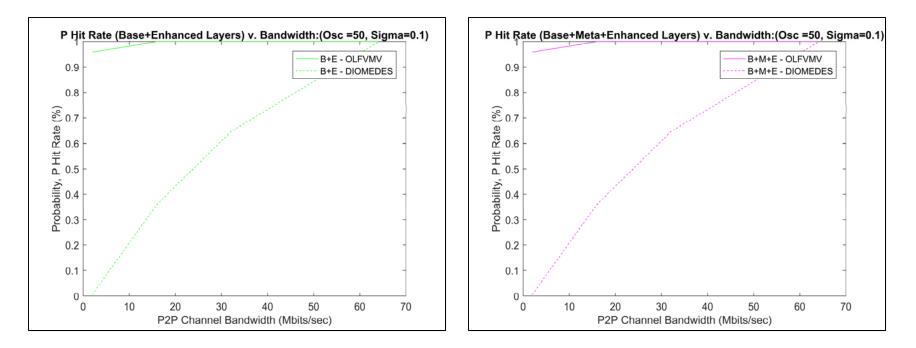
- At a P2P channel bandwidth = 2 Mbps, a slow viewer oscillation rate (Osc = 50 seconds), and with a small viewer variance (sigma scale factor = 0.1) OLFVmv outperformed DIOMEDES by 340%.
 - Nearly 98% of OLFVmv viewers had the desired content at the base layer available
 - while only 29% of DIOMEDES viewers had the desired content at the base layer - DIOMEDES was able to obtain parity only at a P2P channel bandwidth of 64 Mbps





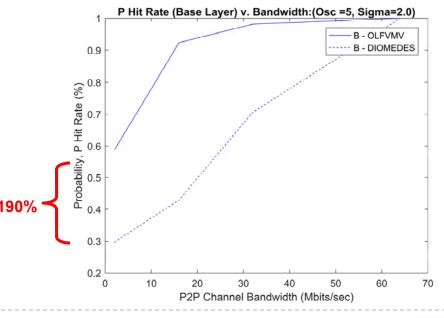
For this same scenario, **DIOMEDES was not capable of transporting** any of the enhanced layer content at 2 Mbps

This is because the P2P channel alone was not capable of transporting the RIGHT core camera enhanced layer (at 4 Mbps) for any viewer.

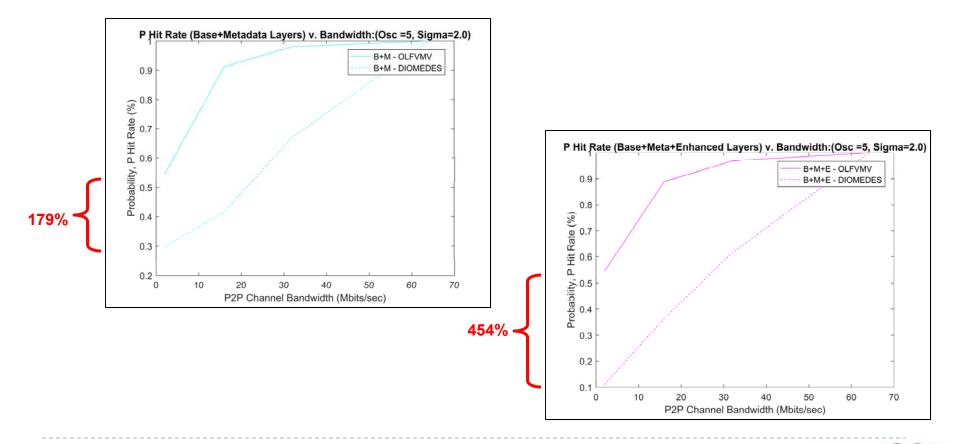




- OLFVmv and DIOMEDES performance was closest to each other when the viewing pattern entailed a rapid oscillation (Osc = 5 seconds) and the randomized dispersion of viewpoints between viewer's was at the highest (sigma scale factor = 2.0)
 - Nonetheless, at P2P bandwidth throughput of 2 Mbps, the performance of OLFVmv exceeded that of DIOMEDES by 190%, for the base layer









Simulation Results - Summary

- OLFVmv's performance far exceeded the performance of DIOMEDES in all cases below 64 Mbps.
- Superior results based on OLFVmv's ability to adaptively sense and prioritize video content.
- OLFVmv provides practical bandwidth requirements.

OLFVmv is important because it opens the door for the use of true live free viewpoint video using standard DVB channels augmented with a limited throughput P2P channel throughput



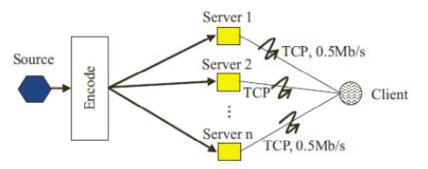
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Future Work: Extensions to OLFVmv Using Hierarchical Network Coding (HNC)

Extensions to HNC are ideally suited for OLFVmv



HNC network path diversity streaming topology showing source and intermediate nodes

Whereas, HNC can be applied to OLFVmv's SVC layering (e.g., base, metadata, enhanced layers) and prioritization of lower priority core camera views

Layer number 1, 2 ... i

$$p_{i} = \sum_{j=1}^{m_{1}} (f_{j}^{1} b_{j}^{1} + \sum_{j=1}^{m_{2}} f_{j}^{2} b_{j}^{2} + .. + \sum_{j=1}^{m_{i}} f_{j}^{i} b_{j}^{i}$$
Original packets for each layer 1, 2 ... i
Non-zero random elements of finite filed F_q
HNC network packet encoding by layers

Oregon State

Future Work: Extensions to OLFVmv Using Hierarchical Network Coding (HNC) (Backup)

HNC inherently accommodates prioritization of OLFVmv layering and core camera views

		Uncoded	WLNC	Hierarchical NC	RNC
	ſ	a_1	a_1	a_1	a_1
Highest priority (thus most	ł	a_2	a_2	a_2	a_2
redundant) e.g, base layer			$a_1 + a_2$	$a_1 + a_2$	$a_1 + a_2$
content or most	ĺ	b_1	b_1	$a_1 + b_1$	$a_1 + b_1$
important core camera views		b_2	b_2	$a_1 + b_2$	$a_1 + b_2$
			$b_1 + b_2$	$a_1 + b_1 + b_2$	$a_1 + b_1 + b_2$
				$a_2 + b_1$	$a_2 + b_1$
Lower priority (thus least				$a_2 + b_2$	$a_2 + b_2$
redundant) e.g.,				$a_2 + b_1 + b_2$	$a_2 + b_1 + b_2$
enhancement layer content or				$a_1 + a_2 + b_1$	$a_1 + a_2 + b_1$
least important core camera				$a_1 + a_2 + b_2$	$a_1 + a_2 + b_2$
views				$a_1 + a_2 + b_1 + b_2$	$a_1 + a_2 + b_1 + b_2$
					b_1
					b_2
					$b_1 + b_2$

COMPARE CODING SCHEMES WITH 2 LAYERS DATA



Future Work: Extensions to OLFVmv Using Hierarchical Network Coding (HNC) (Backup)

Example:

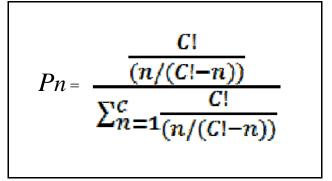
 $pi = \sum_{n=1}^{MAX_CORE_CAMERAS} (\sum_{j=1}^{m_META} f_{n,j}^{META} b_{n,j}^{META} + \sum_{j=1}^{m_BASE} f_{n,j}^{BASE} b_{n,j}^{BASE} +$

 $\sum_{j=1}^{m_{elember and ced}} f_{n,j}^{enhanced} b_{n,j}^{enhanced}$)

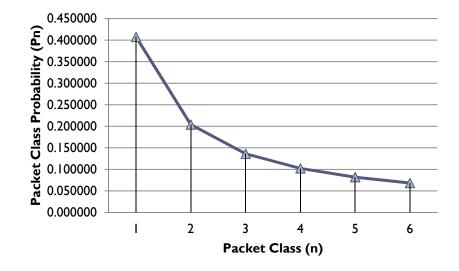
Packet Class (n)	Packet Class Probability (Pn)	Hierarchical NC for FTV Video Content
2	P ₁	$\begin{array}{l} V3_{Base} \\ V3_{Meta} \\ V3_{Enhanced} \\ V3_{Base} + V3_{Meta} \\ V3_{Base} + V3_{Enhanced} \\ V3_{Meta} + V3_{Enhanced} \\ V3_{Base} + V3_{Meta} + V3_{Enhanced} \\ V3_{Base} + V6_{Base} \\ V3_{Base} + V6_{Meta} \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\$
12	P_6	
SUM	= 1	



Future Work: Extensions to OLFVmv Using Hierarchical Network Coding (HNC)(Backup)



Expression of P2P packet priorities within chunks (C = total number of packet classes)



Example - Hierarchical Network Coding (HNC) packet class priorities as applied to FTV core camera video content distribution over the P2P channel

Packet Class	Packet Class Probability				
(n)	(Pn)				
1	0.407339				
2	0.203953				
3	0.136158				
4	0.102261				
5	0.081923				
6	0.068365				
SUM	1.000000				



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 - Algorithms
- Simulation Results
- Extensions to OLFVmv Using Network Coding
- Further Optimization of OLFVmv Ph.D. Thesis Work
- Conclusion



Further Optimization of OLFVmv – Ph.D. Thesis Work

An opportunity exists to *improve viewing trend prediction* algorithms to enhance video content selection and prioritization

- **Objective:** Improved Prediction Modeling/Algorithms Through Reinforcement Learning
- Can our OLFVmv system learn how to best optimize video content prioritization?





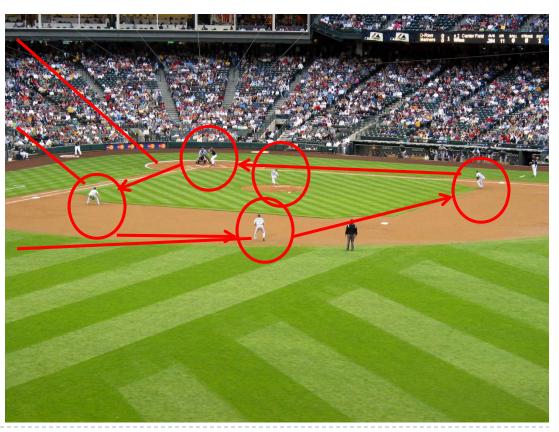
Further Optimization of OLFVmv – Ph.D. Thesis Work

By applying Markov Decision Processes / Reinforcement Learning we can teach the OLFVmv system to optimize video content for *future states*

And various trends

Based on some observed state S

And some other less popular observed states

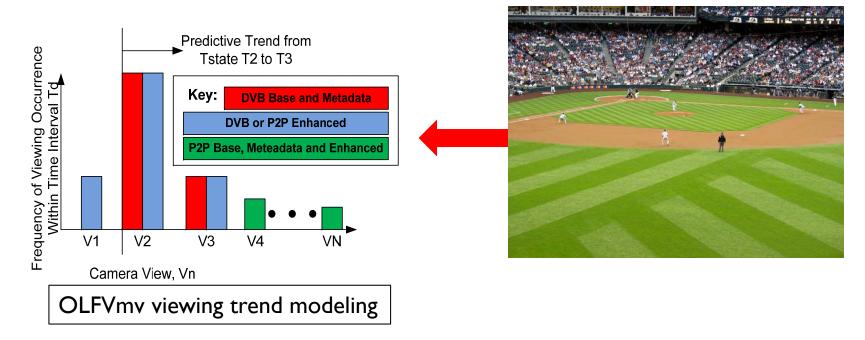




Further Optimization of OLFVmv – Ph.D. Thesis Work

Overall Objectives Deliverables:

- I) Develop machine learning policies
- 2) Emulation on a virtual machine
- 3) Theoretical reconstruction of content packets





Agenda

- Background
 - Video Compression and SVC (Scalable Video Coding)
- Multiview Video Types
 - Multiview Coding (MVC) Types and Industry Standards
- State of the Industry FTV (Free Viewpoint TV)
- OLFVmv (Optimized Live Free Viewpoint multiview video)
 - Motivation
 - Contribution
 - Architecture
 - Algorithms
- Simulation Results
- Extensions to OLFVmv Using Network Coding
- ▶ Further Optimization of OLFVmv Ph.D.Thesis Work

Conclusion

Conclusion

OLFVmv is proven to provide:

- A well defined, practical transport of FTV over existing broadcast mediums¹:
 - Using normal DVB bandwidths
 - Using only 2 DVB channels
- ✓ A practical transport of FTV over P2P networks:
 - Enables low bandwidth, mobile P2P networks using as little as 2 Mbps
- Superior performance over other proposed FTV transport means



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Questions?



